



USER MANUAL

EVALUATION BOARD FOR ABSOLUTE PRESSURE SENSOR PADS

2511223013391

VERSION 2.2

OCTOBER 25, 2024

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Revision history

Manual version	Product version	Notes	Date
1.0	1.0	Initial release of the manual	June 2019
2.0	2.0	 Release of the SPI interface Added PCB layout and assembly diagram in section 3.2 	October 2020
2.1	2.0	 Added Section 1.2 Added Figure 2: Block Diagram Restructured Section 2.1 	February 2021
2.2	2.0	 Updated user manual to new corporate design Added resistor settings for I²C and SPI communication in Resistor functionality Updated section Important notes and Legal notice 	October 2024



Abbreviations

Abbreviation	Description
I ² C	Inter integrated circuit
MEMS	Micro electro mechanical system
LSB	Least significant bit
SPI	Serial Peripheral interface

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1 General description

1.1 Introduction

The EV-Board of the absolute pressure sensor provides an opportunity to verify the sensor performance and develop a prototype using an external processor or an extension board e.g. Sensor Shield for Arduino (Part No. 2501000101291). It can be directly plugged to Amber Pi design kit using the mounted I²C and SPI interface pins. It can also be placed on a bread board using through hole pin header connections. The absolute pressure sensor (Part No: 2511020213301) is a 24-bit compact piezo-resistive digital pressure sensor with an I²C and SPI digital interface.

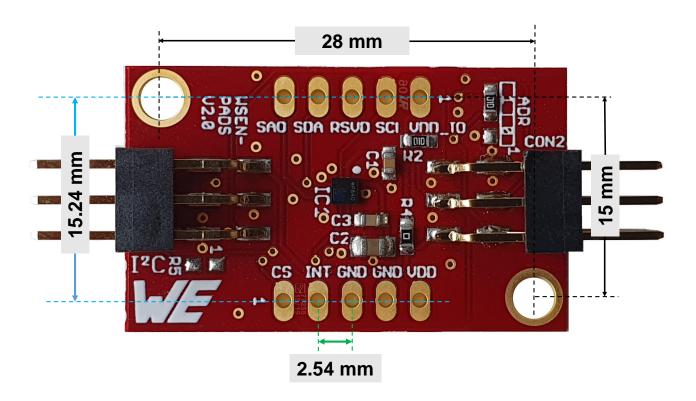


Figure 1: EV-Board for the absolute pressure sensor

1.2 Pin header compatibility

The 6-pin right angle headers mounted on this EV-Board can be directly plugged in to the Sensor Shield for Arduino or Amber-Pi Design Kit. This serves a plug-and-play solution to quickly take the EV-Board into operation.



Sensor Shield for Arduino is a stackable extension board for Arduino UNO and DUE to connect the sensor EV-Boards. More information can be found on our *website*.



2 Functional description

This absolute pressure sensor EV-Board supports the standard I²C and 4-wire SPI communication interface.

- A positive supply voltage is applied to the sensor through VDD pin and I/O supply voltage for digital interface through VDD_IO pin. The VDD and VIO pins on the board are connected together using 0 Ω resistor R1.
- The I²C communication is enabled by connecting CS pin to VDD_IO. The CS pin is connected to VDD_IO using 100 kΩ resistor R3. The I²C address of the sensor can be configured using the SAO pin.
- The 7-bit slave address of the absolute pressure sensor is 101110xb. The LSB of the 7-bit slave address can be modified using the *SAO* pin.

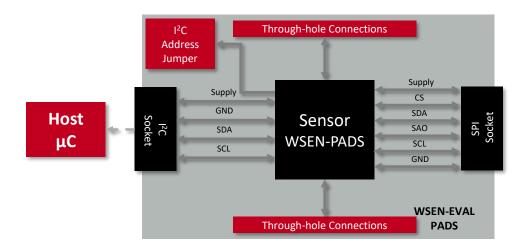


Figure 2: Block diagram of EV-Board for the absolute pressure sensor



By default the 7-bit slave address of the absolute pressure sensor on the EV-Board is 1011101b (0x5D). It can be changed to 1011100b (0x5C) by removing 100 k Ω resistor ADR from '1' part and mounting it on the '0' part of the EV-Board.



Please refer to the data sheet and the user manual of the absolute pressure sensor (Part No: 2511020213301) for more information about the electrical properties and sensor functionality.



2.1 EV-Board in operation

2.1.1 I²C connection (CON1)

The pinning of connector CON1 provides I²C communication interface fits directly to the sensor shield for Arduino as well as Amber-Pi as mentioned in section 1.2.

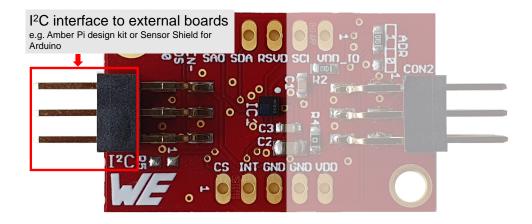
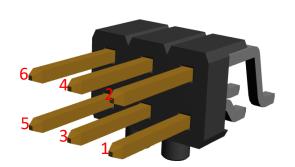


Figure 3: I²C Pin header connection to the external boards



Pin	I ² C pins
1	GND
2	SCL
3	SDA
4	GND
5	INT
6	VDD

Table 1: Pin header to the external boards



When the EV-Board is connected to Amber Pi design kit using I²C interface pins, INT interrupt pin function will not be available.



2.1.2 SPI connection (CON2)

The pinning of connector CON2 provides SPI communication interface fits directly to the sensor shield for Arduino as well as Amber-Pi as mentioned in section 1.2.

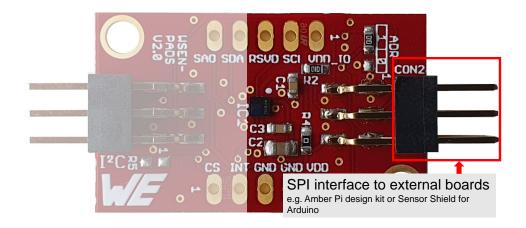
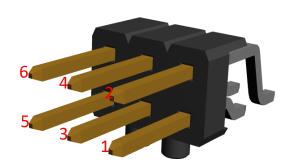


Figure 4: SPI Pin header connection to the external boards



Pin	SPI pins
1	GND
2	SCL
3	SDA (MOSI)
4	CS
5	SAO (MISO)
6	VDD

Table 2: Pin header to the external boards



CS pin is controlled by the host controller (master) when the SPI interface is used.



2.1.3 Resistor functionality

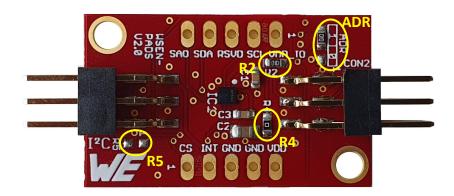


Figure 5: Resistor functionality

Resistor settings for I²C communication

Resistor	Value	Description		
R2	0 Ω	mounted; I ² C enabled. <i>CS</i> is connected to <i>VDD_IO</i>		
R4	0 Ω	mounted; VDD and VDD_IO pins are connected together		
ADR	100 kΩ	Position-1; I ² C address of the sensor is 1011101b. <i>SAO</i> is pulled-up to the <i>VDD_IO</i>		
R5	-	not mounted. optionally can be mounted with 0 Ω to use interrupt functionality on the INT pin		

Table 3: Resistor settings for I²C operation EV-Board

Resistor settings for SPI communication

Resistor	Value	Description		
R2	-	not mounted; CS pin controlled via microcontroller		
R4	0 Ω	mounted; VDD and VDD_IO pins are connected together		
ADR	-	not mounted; SAO pin of sensor works as serial data output		
R5	-	not mounted. optionally can be mounted with 0 Ω to use interrupt functionality on the INT pin		

Table 4: Resistor settings for SPI operation EV-Board



2.1.4 Through hole connection

Through hole pin header connection gives direct access to each sensor pin. To use I²C via these through hole connection, SDA, SCL and INT pins must be connected to VDD_IO via pull-up resistors. SAO pin connection to either VDD or GND is also necessary in order to define an I²C slave address.

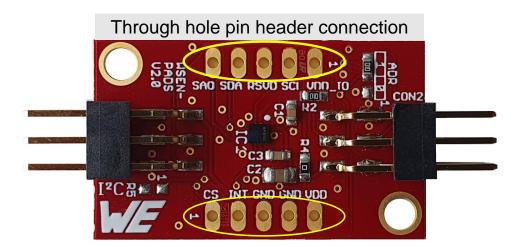


Figure 6: Through hole connection

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Pin No.	Name	Function	I/O	Comments
1	VDD_IO	Positive supply voltage for I/O pins	Supply	
2	SCL	I ² C/SPI serial clock	Input	Internal pull-up disconnected by default
3	RSVD	Reserved	Input	Connect to ground
4	SDA	I ² C serial data; SPI serial data input	Input/ Output	Internal pull-up disconnected by default
5	SAO	I ² C device address selection; SPI serial data output	Input/Output	High: device address LSB is 1 Low: device address LSB is 0
6	CS	I ² C enable/disable; SPI chip select pin	Input	High: I ² C enable
7	INT	Interrupt	Input/Output	Do not connect if not used
8	GND	Negative supply voltage	Supply	
9	GND	Negative supply voltage	Supply	
10	VDD	Positive supply voltage	Supply	

Table 5: Pin description



Check if necessary for your configuration that R2, R4 and ADR resistors have to be removed before connecting the EV-Board to a processor.



3 EV-Board

3.1 Schematic diagram

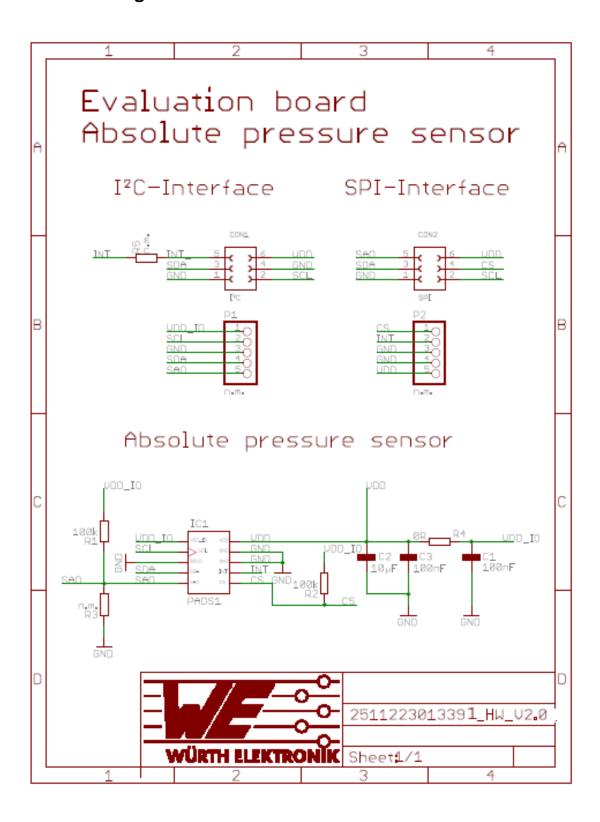


Figure 7: Schematic diagram



3.2 Layout

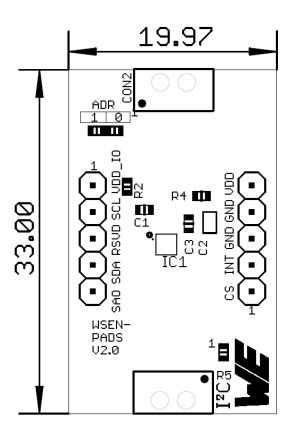
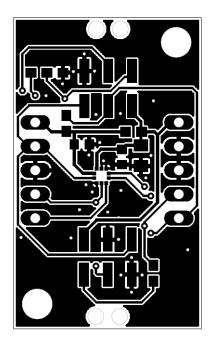


Figure 8: Assembly diagram



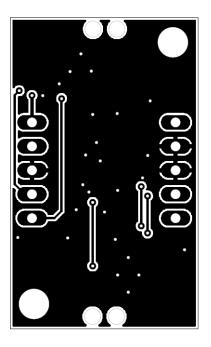


Figure 9: Top (left) and bottom (right) layers

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Miscellaneous

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